



## **Recognizing Languages Definition 3.7.** Formally, a nondeterministic finite-state automaton M is specified by 5 components: $M = (Q, \Sigma, q_0, \partial, F)$ where • $Q, \Sigma, q_0$ and F are as in the definition of DFAs; • $\partial$ is a transition function that takes <state, input symbol> pairs and maps each one to a set of states. To say $\partial(q, a) = \{q_1, q_2, \dots, q_n\}$ means that if the machine is in state q and the input symbol a is consumed, then the machine may move directly into any one of states $q_1, q_2, \ldots, q_n$ . The function $\partial$ must also be defined for every $\langle \text{state}, \varepsilon \rangle$ pair. To say $\partial(q,\varepsilon) = \{q_1, q_2, \dots, q_n\}$ means that there are direct $\varepsilon$ transitions from state q to each of $q_1, q_2, \ldots, q_n$ . The formal description of the function $\partial$ is $\partial: Q \times (\Sigma \cup \{\varepsilon\}) \to \mathcal{P}(Q)$ . NDFAs allow - more than one transition involving the same state and symbol $-\partial(q,a)$ is a set ε-transitions – can change state without consuming input

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## **Recognizing Languages**

**Definition 3.7.** Formally, a nondeterministic finite-state automaton M is specified by 5 components:  $M = (Q, \Sigma, q_0, \partial, F)$  where

- $Q, \Sigma, q_0$  and F are as in the definition of DFAs;
- ∂ is a transition function that takes <state, input symbol> pairs and maps each one to a set of states. To say ∂(q, a) = {q<sub>1</sub>, q<sub>2</sub>,..., q<sub>n</sub>} means that if the machine is in state q and the input symbol a is consumed, then the machine may move directly into any one of states q<sub>1</sub>, q<sub>2</sub>,..., q<sub>n</sub>. The function ∂ must also be defined for every <state, ε> pair. To say ∂(q, ε) = {q<sub>1</sub>, q<sub>2</sub>,..., q<sub>n</sub>} means that there are direct ε-transitions from state q to each of q<sub>1</sub>, q<sub>2</sub>,..., q<sub>n</sub>.
  The formal description of the function ∂ is ∂ : Q × (Σ ∪ {ε}) → P(Q).

 $\begin{array}{l} \text{accept } w \\ \text{fit is} \\ \text{automaton. The string } w \in \Sigma^* \text{ is accepted by } M \text{ iff } \partial^*(q_0, w) \text{ contains at} \\ \text{least one state } q_F \in F. \\ \text{The language accepted by } M, \text{ denoted } L(M), \text{ is the set of all strings} \\ w \in \Sigma^* \text{ that are accepted by } M: L(M) = \{w \in \Sigma^* \mid \partial^*(q_0, w) \cap F \neq \emptyset\}. \end{array}$ 

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## Equivalence of DFAs and NDFAs

- every language accepted by a DFA is accepted by an NDFA
  - a DFA is (essentially) an NDFA NDFA does not require multiple or  $\varepsilon$ -transitions, and for  $\delta(q,a) = q'$ ,  $\partial(q,a) = \{q'\}$
- every language accepted by an NDFA is accepted by a DFA

**Theorem 3.2.** Every language that is accepted by an NFA is accepted by a DFA.

 proof idea: give an algorithm for constructing an equivalent DFA from an NDFA (then prove the algorithm correct)

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