

THEOREM 0.0.1 (The Onto Dictionary). Let A be an $m \times n$ matrix and let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ with standard matrix A . Then the following are equivalent.

- (a) A has m pivots positions
- (b) A has pivot in every row
- (c) For any $\mathbf{b} \in \mathbb{R}^m$, the system $A\mathbf{x} = \mathbf{b}$ is consistent
- (d) Any $\mathbf{b} \in \mathbb{R}^m$ is a linear combination of the columns of A
- (e) The columns of A span \mathbb{R}^m
- (f) $\text{Col } A = \mathbb{R}^m$
- (g) $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is onto

THEOREM 0.0.2 (The One-to-One Dictionary). Let A be an $m \times n$ matrix and let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ with standard matrix A . Then the following are equivalent.

- (a) A has n pivots positions
- (b) A has pivot in every column (no free variables)
- (c) $A\mathbf{x} = \mathbf{0}$ has only the trivial solution $\mathbf{x} = \mathbf{0}$
- (d) $\text{Nul } A = \{\mathbf{0}\}$
- (e) The columns of A are independent
- (f) $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is one-to-one

THEOREM 0.0.3 (The Connections Theorem). Let A be an $n \times n$ matrix and let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ with standard matrix A . Then the following are equivalent.

- (a) A is non-singular
- (b) $A \sim I_n$
- (c) A has n pivots positions
- (d) A has pivot in every row
- (e) For any $\mathbf{b} \in \mathbb{R}^n$, the system $A\mathbf{x} = \mathbf{b}$ is consistent
- (f) Any $\mathbf{b} \in \mathbb{R}^n$ is a linear combination of the columns of A
- (g) The columns of A span \mathbb{R}^n
- (h) $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is onto
- (i) A has pivot in every column (no free variables)
- (j) $A\mathbf{x} = \mathbf{0}$ has only the trivial solution $\mathbf{x} = \mathbf{0}$
- (k) The columns of A are independent
- (l) $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is one-to-one
- (m) There is an $n \times n$ matrix C such that $CA = I_n$
- (n) There is an $n \times n$ matrix D such that $AD = I_n$
- (o) A^T is invertible
- (p) For any $\mathbf{b} \in \mathbb{R}^n$, the system $A\mathbf{x} = \mathbf{b}$ has a *unique* solution
- (q) $\det A \neq 0$
- (r)
- (s)

Reading and Practice

1. Practice: Section 4.2. Page 205–207: #1, 3, 5, 7, 9, 11, 15, 17, 19, 21, 23, 25. These problems are great and a bit harder: Page 235 #31, 33, and 35 (Challenge! XC).
2. Coming up next: Read Section 4.3 on Bases.

Hand In Monday

0. Remember the WeBWorK problem set due Tuesday

1. Let $\mathbb{U} = \left\{ \begin{bmatrix} a+2 \\ 2a \\ b-a \end{bmatrix} : a, b \in \mathbb{R} \right\}$. Determine whether \mathbb{U} is a subspace of \mathbb{R}^3 . Be sure to justify your answer.

2. Assume A is $n \times n$. Prove: If $\text{Nul } A = \{\mathbf{0}\}$, then $\det A^T \neq 0$.

3. Background: Let \mathcal{F} be the vector space of all functions defined on $(-\infty, \infty)$. Let $\mathcal{C} = \{f \in \mathcal{F} : f \text{ is continuous}\}$. We can check that \mathcal{C} is a subspace of \mathcal{F} . The zero function $\mathbf{0}(t) = 0$ is continuous so it is in \mathcal{C} . If f and g are both in \mathcal{C} , then both are continuous, so from Calculus I their sum $f + g$ is also continuous. So $f + g \in \mathcal{C}$. If c is a scalar and f is in \mathcal{C} , then f is continuous and from Calculus I, cf is also continuous. So $cf \in \mathcal{C}$. So \mathcal{C} is a subspace of \mathcal{F} . Now here's the problem:

(a) Let $T : \mathcal{C} \rightarrow \mathbb{R}$ by $T(f) = \int_0^1 f(x) dx$. Show that T is a linear transformation. You will need to use your Calculus II knowledge.

(b) Bonus: Find an example of a function f in $\ker T$ such that f is not the zero function.

4. (a) Let $T : M_{2 \times 2} \rightarrow \mathbb{R}^2$ by $T(A) = T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a-c \\ b+d \end{bmatrix}$. Is T a linear transformation? Prove your result.

(b) Describe the form of the matrices in $\ker T$ in terms of their component entries. In other words,

$$\ker T = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : \text{some condition(s) involving } a, b, c, d \right\}.$$

Bonus if you can write them as the span of a set of vectors (matrices) in $M_{2 \times 2}$.

5. (a) Complete the following: If A is $n \times n$, then $\det(cA) = \underline{\hspace{2cm}}$

(b) Let $T : M_{2 \times 2} \rightarrow \mathbb{R}$ by $T(A) = \det(A)$. Determine whether T is a linear transformation. Hint: In light of part (a), which property of a linear transformation should you check first.

6. **Bonus.** Let H and K be subspaces of a vector space \mathbb{V} . The **intersection** of H and K , written as $H \cap K$, the set of vectors \mathbf{v} in \mathbb{V} that belong to both H and K . Prove that $H \cap K$ is a subspace of \mathbb{V} . [You will need to use the fact that H and K are both subspaces of \mathbb{V} to verify the three subspace conditions.]

7. **EZ Small Extra Credit.** This problem is fairly easy. But if you need practice with subspace proofs, here's one more. Since this is a straightforward bonus problem, it should be done carefully and perfectly. Let \mathbf{x} be some fixed (but unknown) vector in \mathbb{R}^n . Let

$$H = \{A \in M_{m \times n} : A\mathbf{x} = \mathbf{0}\}.$$

Is H a subspace of $M_{m \times n}$?

Coming Next Week

8. (a) Let $T : M_{2 \times 2} \rightarrow M_{2 \times 2}$ by $T(A) = A + A^T$. Is T a linear transformation? Prove your result carefully.

(b) Describe the form of the matrices in $\ker T$ in terms of their component entries.

$$\ker T = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : \text{some condition(s) involving } a, b, c, d \right\}.$$