

## Graph Traversal

One of the basic things you can do with any collection is *traversal* – i.e. visit everything in the collection exactly once.

- for graphs, this is vertices and edges
- need a systematic method to ensure
  - correctness – don't leave anything out
  - efficiency – don't waste time visiting the same things over and over

## Graph Traversal

Building blocks and observations –

- Graph ADT provides operations for getting edges incident on a vertex, and end vertices of an edge
  - from a vertex you can find edges, and from an edge you can find the vertex at the other end
- there may be more than one vertex adjacent to another –
  - can't just trace through the graph using a single finger to point at where you are (loop)
  - the possibility of cycles means it is necessary to know what has been visited already
    - need a container to hold *discovered* vertices

Using a queue for the container leads to breadth-first search.

## Breadth-First Search

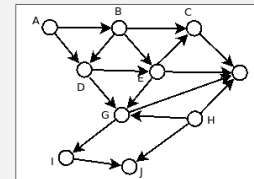
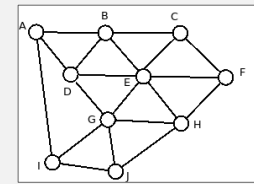
```
bfs(G,s)  G is the graph, s is the starting vertex
for each vertex u in V-{s} do
  state[u] = "undiscovered"
  prev[u] = null
state[s] = "discovered"
prev[s] = null
Q.enqueue(s)  Q is the queue of discovered vertices
while Q is not empty do
  u = Q.dequeue()
  process vertex u (early)  "process" is application-specific
  for each edge (u,v) in G.incidentEdges(u) do
    if state[v] = "undiscovered" then
      process edge (u,v)
      state[v] = "discovered"
      prev[v] = u
      Q.enqueue(v)
state[u] = "processed"
process vertex u (late)
```

this is a generalized form of the algorithm which allows for both early (before visiting incident edges) and late (after visiting incident edges) operations

## Class Prep – BFS

regraded – issue with the correct answer specified  
write the vertex names as shown – capital letters

```
bfs(G,s)
for each vertex u in V-{s} do
  state[u] = "undiscovered"
  prev[u] = null
state[s] = "discovered"
prev[s] = null
Q.enqueue(s)
while Q is not empty do
  u = Q.dequeue()
  for each edge (u,v) in G.incidentEdges(u) do
    if state[v] = "undiscovered" then
      state[v] = "discovered"
      prev[v] = u
      Q.enqueue(v)
state[u] = "processed"
```



H is unreachable starting from A –  
it is never marked as processed

	adjacency list	adjacency matrix
numVertices(), numEdges()	O(1)	O(1)
vertices(), edges()	O(1) per element	O(1) per element
aVertex()	O(1)	O(1)
degree(v)	O(1)	O(1)
adjacentVertices(v)	O(1) per element	O(n) – to scan row/column of array
incidentEdges(v)	O(1) per element	O(n) – to scan row/column of array
endVertices(e)	O(1)	O(1)
opposite(v,e)	O(1)	O(1)
areAdjacent(v,w)	O(min(deg(v,w))) – search list for vertex with smaller degree	O(1)
insertEdge(v,w,o)	O(1)	O(1)
insertVertex(o)	O(1)	O(n) – to initialize row/col of array O(n <sup>2</sup> ) – if array needs to grow
removeVertex(v)	O(deg(v)) – to remove each incident edge	O(1) – with clever bookkeeping (and wasted space) O(n <sup>2</sup> ) – shifting in array
removeEdge(e)	O(1)	O(1)
space	O(n+m)	O(n <sup>2</sup> )

## BFS – Implementation and Running Time

```

bfs(G,s)
for each vertex u in V-{s} do
    state[u] = "undiscovered"
    prev[u] = null
state[s] = "discovered"
prev[s] = null
Q.enqueue(s)
while Q is not empty do
    u = Q.dequeue()
    for each edge (u,v) in G.incidentEdges(u) do
        if state[v] = "undiscovered" then
            state[v] = "discovered"
            prev[v] = u
            Q.enqueue(v)
        state[u] = "processed"

```

O(1) per element → O(n) total  
 enqueue, dequeue, isEmpty are O(1)  
 set, access state – want O(1), can do that with Map (hashtable)

O(1) per element = O(deg(u)) (adj list)  
 O(n) (adj matrix)

total over all iterations of while loop –  
 • O(m) for adj list because the sum of the degrees is 2m – each edge is counted twice  
 • O(n<sup>2</sup>) for adj matrix because while loop repeats n times

total over all iterations of while loop – O(n)

O(n+m) for adjacency list implementation  
 O(n<sup>2</sup>) for adjacency matrix implementation