

HW 10

- give the steps of the backtracking process from class, not just a statement of the algorithm or a narrative account of your reasoning process
- establish the problem
 - specifications
 - examples
- identify avenues of attack
 - targets
 - paradigms and patterns
 - the series of choices
- define the algorithm
 - size
 - generalize / define subproblems: partial solution, alternatives, subproblem
 - base case(s)
 - main case
 - top level: initial subproblem, setup, wrapup
 - special cases
 - algorithm
- show termination and correctness
 - termination: making progress, the end is reached
 - correctness: establish the base case, show the main case, final answer
- determine efficiency
 - implementation
 - time and space
 - room for improvement
- only #3, #4 were graded (or a different problem if you didn't hand in #3, #4)
 - review those comments and consider their application to the other problems

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- there are different ways to structure elements of backtracking algorithms – be careful to be consistent with your choices
 - the subproblem solution can be either a complete solution (including the partial solution) or just the solution for the rest of the problem (not including the partial solution)
 - the framework and examples discussed in class use the former (complete solution) for backtracking and the latter (rest of the problem) for dynamic programming
 - for find-the-best-solution tasks, either return the best solution or update a global best-so-far
 - return the best: base case returns the complete solution it got, main case maintains a best-so-far solution from amongst the subproblems it generates and returns that
 - update global: base case checks its complete solution against the global best so far and updates accordingly, nothing is returned

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- for any algorithm, highly detailed pseudocode is not helpful in understanding the concept and its correctness
 - words are good!
 - introduce notation only when it is clearer than words
 - especially stick with words when notation forces you into unnecessary implementation decisions
 - don't be tempted to overload notation with additional meanings
 - e.g.
 - good: "remove contractor c from the available contractors" or "mark contractor c as unavailable" or "available.remove(c)"
 - all convey that c is no longer available
 - confusing: `unavailable ← c`
 - \leftarrow is a common convention in pseudocode for assignment, so using it to mean adding c to a collection is confusing

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- pruning
 - pruning if the partial solution cost > best-so-far cost is safe (and cheap)...
 - ...but any partial solution cost will generally be lower than a complete solution cost because there are fewer jobs with contractors assigned in a partial solution (unassigned jobs have a cost of 0)
 - pruning based on some estimate of the cost of the rest of the solution is branch and bound

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- bound functions
 - be aware of running time – the bound function must be evaluated for every subproblem even if no pruning occurs
 - global best value \times number of choices left is $O(1)$ to compute
 - summing something over the remaining choices is $\Omega(n-k)$ (k choices made, $n-k$ choices left)
 - $O(n-k)$ if the value being summed can be determined in $O(1)$ for each choice
 - there is often a tradeoff between pruning quality and speed – find the best balance
 - global best value \times number of choices left is $O(1)$ to compute – but may not be very close to the actual solution cost
 - possible $\Omega(n-k)$ strategies
 - choose the best alternative for each of the remaining choices ignoring legality
 - safe – no legal alternative can be better than the best possible one
 - choose the best legal alternative (based on the current partial solution) for each of the remaining choices
 - safe – later alternatives, when fewer alternatives are available, can't be better than the best alternative now
 - greedy solution
 - not safe – picking a good alternative now may force a worse alternative later