

## Analysis of Algorithms

### Motivation

A good algorithm is  
**correct**,  
**efficient**, and  
**easy to implement**.

- answering “how much time/space does this algorithm take?” and “can we do better?” requires a measure of the time/space requirements

### Key Points

We want to **compare algorithms**, not programs.

- the elapsed time of a running program depends on many factors unrelated to the algorithm
  - speed of computer
  - computer architecture
  - choice of language, skill/cleverness of programmer, compiler optimizations
- implementing and debugging a program is time consuming
  - requires too many details

### RAM Model of Computation

Assumptions –

- each simple operation takes exactly one time step
  - arithmetic, boolean, logical operations; `=`; `if`; subroutine calls
    - ⚠ `=`, `if` is the assignment or branch itself, not the evaluation of expressions or the execution of the body of a branch
    - ⚠ subroutine call is just the call and return, not the execution of the subroutine body
- each memory access takes exactly one time step
- expressions and blocks are not simple operations
- loops are not simple operations
  - composed of (many) simple operations
  - time required is the sum of the time required for each simple operation

## Key Points

Those assumptions are actually false with respect to real computers.

Even though our analyses will be based on a model of computation that is **not** how real computers work, all is not lost –

- still meaningful
  - it is difficult to find a case where it gives misleading results
- simplifies analysis
  - allows for reasoning about algorithms in a language- and machine-independent manner

## Key Points

We are actually more interested in **how quickly the running time of an algorithm increases as the size of the input increases** than in how long the algorithm will take on a particular input instance.

- still meaningful
  - a single input instance may not be all that informative anyway
  - any algorithm will be fine when the input is small – it's what happens for big inputs that matters
- simplifies analysis
  - means we don't need to count precisely – can focus on how the number of steps depends on aspects of the input
  - can consider (only) best and worst-case bounds
    - fewer cases to consider, and easier to work with an input instance with specific properties

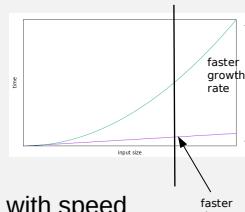
## Key Points

We are actually even more interested in **categorizing algorithms into a few common classes** than determining specific growth rate functions.

- still meaningful
  - the differences within one class are far less than the differences between classes
- simplifies analysis
  - can drop constant factors and lower order terms (eliminating distracting bumps)
  - can analyze algorithm at a higher level of abstraction (pseudocode or even natural language description rather than code)

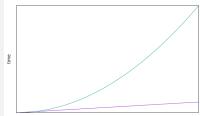
## Understanding Limitations

Alice and Bob each implement different algorithms for solving a particular problem. When they run their programs, they find that the one with the slower growth rate takes longer. What could be going on?



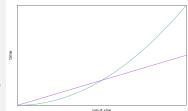
- be careful not to confuse growth rate with speed
  - the *speed* refers to the running time for a particular input
    - faster speed = takes less time
  - the *growth rate* refers to how quickly the running time increases
    - slower growth rate means the running time doesn't increase as quickly – the running time is smaller/shorter/faster for longer
  - the question is how an algorithm with a slower growth rate could take *more* time on an input than one with a faster growth rate

## Understanding Limitations



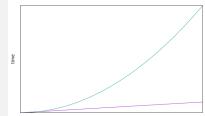
how can an algorithm A with a slower growth rate take *more* time on an input than algorithm B with a faster growth rate?

- $n$  is small – constant factors and lower-order terms have a greater impact on running time for small  $n$
- there could be different environments – language, programmer cleverness, compiler optimizations, computer speed, ...
- “growth rate of algorithm” typically refers to the growth rate of the worst-case running time
  - input instance used may not be worst case for B



9

## Understanding Limitations



how can an algorithm A with a slower growth rate could take *more* time on an input than algorithm B with a faster growth rate?

Or it might not have been a fair test –

- different inputs used e.g. A's input was bigger
- (really) inefficient implementation of A
  - e.g. looping through whole array instead of only accessing one slot
- A takes more space, making it slower
  - each memory access is assumed to take one time step so the running time puts a limit on how much space A can use
  - A's computer could be pushed into swapping while B's is not
    - constant factors could mean that A's memory usage exceeds B's
    - A's computer could have less memory

10

## Definitions

- $O$  gives an *upper bound* on a function's growth rate
- $\Omega$  gives a *lower bound* on a function's growth rate
- $\Theta$  gives a *tight bound* on a function's growth rate

notation	meaning	definition
$f(n) = O(g(n))$	$c g(n)$ is an upper bound on $f(n)$	there exists $c > 0$ and $n_0 > 0$ such that $f(n) \leq c g(n)$ for all $n \geq n_0$
$f(n) = \Omega(g(n))$	$c g(n)$ is an lower bound on $f(n)$	there exists $c > 0$ and $n_0 > 0$ such that $f(n) \geq c g(n)$ for all $n \geq n_0$
$f(n) = \Theta(g(n))$	$c_1 g(n)$ is an upper bound on $f(n)$ $c_2 g(n)$ is an lower bound on $f(n)$	there exists $c_1 > 0$ , $c_2 > 0$ , and $n_0 > 0$ such $f(n) \leq c_1 g(n)$ and $f(n) \geq c_2 g(n)$ for all $n \geq n_0$

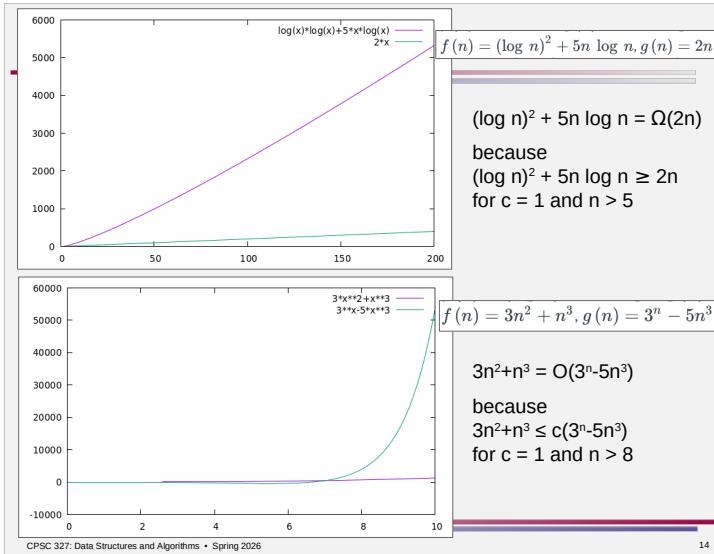
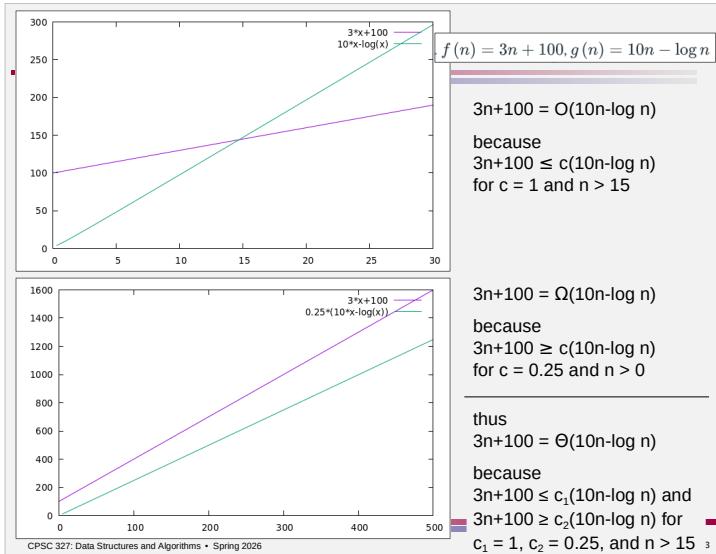
## Understanding Definitions

For each of the following pairs of functions, indicate whether  $f = O(g)$ ,  $f = \Omega(g)$ , or  $f = \Theta(g)$ .

- $f(n) = 3n + 100$ ,  $g(n) = 10n - \log n$  [pairA]
- $f(n) = (\log n)^2 + 5n \log n$ ,  $g(n) = 2n$  [pairB]
- $f(n) = 3n^2 + n^3$ ,  $g(n) = 3^n - 5n^3$  [pairC]

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## $O, \Omega, \Theta$ vs Best and Worst Cases

The big-Oh notation compares growth rates of functions – comparing shapes of curves.

- $f(n) = O(g(n))$  says that  $f(n)$  grows no faster than  $g(n)$ 
  - $g(n)$  is an upper bound on the growth rate
- $f(n) = \Omega(g(n))$  says that  $f(n)$  grows no slower than  $g(n)$ 
  - $g(n)$  is a lower bound on the growth rate
- $f(n) = \Theta(g(n))$  says that  $f(n)$  grows at the same rate as  $g(n)$ 
  - $g(n)$  is a tight bound on the growth rate

The best (or worst) case is the specific input instance that yields the fastest (or slowest) running time over all possible input instances of a given size – comparing the actual number of steps required.

- no input instance will take longer than the worst case for that size, or take less time than the best case for that size

## Understanding Terminology and Concepts

If Alice proves that an algorithm takes  $O(n^2)$  worst-case time, is it possible that it takes  $O(n)$  time on some inputs?

If Alice proves that an algorithm takes  $O(n^2)$  worst-case time, is it possible that it takes  $O(n)$  time on all inputs?

If Alice proves that an algorithm takes  $\Theta(n^2)$  worst-case time, is it possible that it takes  $O(n)$  time on some inputs?

- yes** – worst-case means no case is slower, but faster is possible

- yes** –  $O$  is an upper bound, so  $f(n) = O(n^2)$  says that  $f(n)$  doesn't grow any faster than  $n^2$ , but it doesn't preclude it growing slower i.e.  $n = O(n^2)$  though typically we want to give the tightest bound we can

- yes** –  $\Theta$  means that the worst case won't actually turn out to be better than  $n^2$ , but the worst case is the slowest input of a given size and others (e.g. best case) may be better

## O, $\Omega$ , $\Theta$ vs Best and Worst Cases

Saying that the worst-case behavior is  **$O(n^2)$**  means –

- some inputs could be  $O(n)$  because the worst case is the slowest instance for a given size
- all inputs could be  $O(n)$  because  $n$  grows no faster than  $n^2$ , though one generally tries to give the tightest  $O$  possible

Saying that the worst-case behavior is  **$\Theta(n^2)$**  means –

- some inputs could be  $O(n)$  because the worst case is the slowest instance for a given size
- not all inputs could be  $O(n)$  because then the worst case instances would also be  $O(n)$  and  $n$  does not grow at the same rate as  $n^2$

## O, $\Omega$ , or $\Theta$ ?

- give as tight as bound as possible
- use  $\Theta$  if you can
  - e.g. mergesort is  $\Theta(n \log n)$
  - e.g. insertion sort is best case  $\Theta(n)$  and worst case  $\Theta(n^2)$
- can use  $O$  if best case running time grows more slowly than the worst case but you don't want to distinguish – only the worst case is important
  - e.g. insertion sort is  $O(n^2)$
- can use  $\Omega$  if worst case running time grows faster than the best case but you don't want to distinguish – only the best case is important
  - e.g. insertion sort is  $\Omega(n)$
- can use  $O$  (or  $\Omega$ ) if you can't establish a tight bound
  - you don't know if the best case is better or if the worst case is worse