Patterns for Motion

There are two ways to change the position of something –

- update position: position = position + speed
 - simple motion (constant speed) speed is fixed
 - random walk speed is random
 - acceleration/deceleration update speed by a fixed amount
- compute position directly using equations: position = ...
 - random position use random(low, high) or noise(t)
 - constrained motion x and y coordinates aren't independent

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Random Position

Random position –

use random(low, high) to compute x and y separately

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Implementing Directly Computed Positions

- local variable(s) for position (x, y)
 - declaration, initialization, and usage only no update
- pattern
 - create a new block containing the statement(s) where the position is used
 - this limits the scope of the variables to the block
 - declare and initialize position at the beginning of the block
 - can combine into a single statement

Smoothly-Varying Random Position

Random position, with "natural" (smoother) randomness -

- use noise(t) to compute x and y separately
 - t is an animation variable declare, initialize, use, update
 - map scales the noise value (between 0 and 1) to the range you want (drawing coordinates)

```
float t;
                            // perlin noise parameter for circle
void setup () {
                      initialization value is arbitrary -
                      controls the sequence of values
  t = \theta:
                          noise produces a value
void draw () {
                                                  want to draw circle
                          between 0 and 1
                                                 somewhere within
                                                 the window
     float x = map(noise(t), 0, 1, 15, width-15); // pos of circle
    ellipse(x, height/2, 30, 30); // draw circle
                         size of update of t controls
  t = t+.01: -
                         smoothness of the random numbers
                         (smaller value = smoother)
```

On a ramp, the object's position is constrained to be along a particular line. - xspeed and yspeed aren't independent – there must be a certain relationship between the amount of change in the x coordinate and in the y coordinate if the ellipse moves distance dx horizontally, how far does it have to move vertically in order to stay on the ramp?

Parametric Equations

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The *parametric equations* for a curve express the coordinates of the points on the curve in terms of functions of an independent *parameter*.

$$x = f(t)$$

 $y = f(t)$

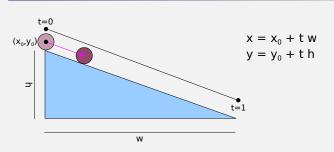
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Constrained Motion — Circular Motion

if the ellipse moves distance dx horizontally, how far does it have to move vertically in order to stay on the circle?

This question is harder for circles than for ramps, because there's not a fixed ratio relating dy to dx.

Parametric Equations – Ramps



- w, h are the dimensions of the ramp
- (x₀,y₀) is determined by the position of the ramp and the size of the object on the ramp
- t is the parameter increasing t moves along the ramp
 - 0 ≤ t ≤ 1 (other values are legal, but are beyond the span of the $\frac{1}{2}$ ramp)

Parametric Equations – Circular Motion

$$x = c_x + r \cos t$$

$$y = c_y + r \sin t$$

$$(c_x, c_y)$$
• (c_x, c_y) is the center of the circle
• r is the radius of the circle

• t is the parameter – increasing t moves around the circle

- t is in radians, so $0 \le t \le 2*PI$ covers one revolution

Implementing Constrained Motion

- animation variable t
 - declare, initialize (usually to 0), use (to determine position), update (size of update controls speed)
- local variable(s) for position
 - compute position using parametric equations