

## Heaps – Implementation

Arrays are the traditional implementation for heaps.

- same big-Oh as linked structure, but avoids space overhead of parent/child pointers

Running time:

- insert –  $O(\log n)$ 
  - $O(1)$  to put element in array, update last
  - $O(\log n)$  to bubble up
- remove min –  $O(\log n)$ 
  - $O(1)$  to swap with last, remove last, update last
  - $O(\log n)$  to bubble down
- find min –  $O(1)$ 
  - min element is at root (index 0)

## Heaps – Implementation

We didn't improve the big-Oh over the balanced search tree implementation for PQs.

But –

- reduced storage overhead (no parent, child pointers)
- reduced difficulty of implementation
  - array + bubble up, bubble down vs. linked structure + balanced search tree operations
  - traded maintaining 'min' reference for incrementing/decrementing 'last' index
- reduced constant factors
  - traded  $O(\log n)$  maintenance of 'min' reference for  $O(1)$  maintenance of 'last' index

## Building a Heap

How to build a heap?

- repeatedly insert each element  $\sum_{i=0}^{n-1} \log(i) = \Theta(n \log n)$

## Building a Heap

Or...if you already have an array of elements...

- for any  $n$  elements in an array, the heap order property is at most broken only for the first  $n/2$  elements

Heapify idea.

- for each index  $n/2$  down to 0, bubble down that element

Running time.

- bubble down takes  $O(h)$  time
  - $n/2$  elements are leaves (already in place – no change)
  - $n/4$  elements are one level above leaf (at most 1 swap)
  - $n/8$  elements are two levels above leaf (at most 2 swaps)
  - ...

$$= \sum_{i=1}^{\log n} (i-1) \left(\frac{n}{2^i}\right) = n \Theta(1) = \Theta(n)$$