

## Proving NP-Completeness

Most NP-complete problems are proven NP-complete by a reduction to a known NP-complete problem.

If problem A has a polynomial-time reduction to problem B, which of the following can you conclude?

If A is NP-complete, there can't be a polynomial-time algorithm for B	3 respondents	60 %	<div><div></div></div> ✓
if B is NP-complete, there can't be a polynomial-time algorithm for A	2 respondents	40 %	<div><div></div></div>
none of the above		0 %	<div><div></div></div>

## Reduction Example

### Course scheduling –

Given a set of courses requested by each student, a set of time slots, and an integer  $k$ , determine if there is an assignment of courses to time slots with at most  $k$  conflicts amongst the students' schedules.

Is course scheduling in NP?

True	4 respondents	80 %	<div><div></div></div> ✓
False	1 respondent	20 %	<div><div></div></div>

- yes
  - it is a decision problem (yes/no question)
  - a 'yes' answer is verifiable in polynomial time – given an assignment of courses to time slots, one simply needs to go through each student's schedule and count conflicts

Is course scheduling NP-complete?

## Reduction Example

### Course scheduling –

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Is course scheduling NP-complete?

- we need a known NP complete problem to reduce to this problem

### 3-coloring –

Determine if you can color a graph with three colors so that no two adjacent nodes have the same color.

- known to be NP-complete

## Reduction Example

Reduce an instance of 3-coloring to an instance of course scheduling:

- vertices → courses
- edges → students
  - each student will have two requested courses, corresponding to the two vertices connected by the edge
- colors → timeslots
  - there will be three timeslots, corresponding to the three colors
- legal coloring →  $k = 0$ 
  - an illegal 3-coloring means two adjacent nodes with the same color – this corresponds to a student whose courses are scheduled in the same timeslot
  - a schedule with no conflicts thus means a legal 3-coloring

This construction only takes polynomial time.

- traverse the graph –  $O(n)$  to create courses for  $n$  vertices,  $O(m)$  to create students for  $m$  edges,  $O(1)$  to create three timeslots

remember that reducing A to B means that B is at least as hard as A

- B can't be easier than A, or else we'd have a better algorithm for A
- A could be easier than B, because there may be another algorithm for A

## Reduction Example

Thus, course scheduling is also NP-complete.

- if course scheduling could be solved in polynomial time, so could 3-coloring
- if 3-coloring can be solved in polynomial time, so can everything else in NP

## Direction of Reductions Matters!

A sudoku puzzle is an instance of an exact cover problem, meaning that sudoku can be reduced to exact cover.

- exact cover: given a collection of subsets of  $X$ , is there a group of those subsets such that every element of  $X$  is contained in exactly one subset?

8			4	6		7
	1				4	5
5	9		3	7	8	
	4	8		7	1	3
	5	2				9
		1				
3			9	2		5

Exact cover is NP complete.

Does this mean sudoku is NP complete too?

- not necessarily – the hard problem (exact cover) can be used to solve sudoku, but maybe there's some other way to solve sudoku more efficiently

## Proving NP-Completeness

But how do you get a known NP-complete problem in the first place?

- need a direct proof!

[1971] Cook-Levin theorem proved SAT is NP-complete.

$(x_1 \vee x_2) \wedge (x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2)$  SAT: is there an assignment of values to variables in a boolean expression so that the expression evaluates to TRUE?

Idea:

- start with a nondeterministic Turing machine which solves some problem in NP
- for each possible input, build a boolean expression which is satisfiable if and only if the machine accepts the input (a “yes” response)

Then solving satisfiability tells whether or not the machine accepts the input, so satisfiability cannot be easier than the NP problem. (And since this construction can be done for any NP problem, satisfiability cannot be easier than any NP problem.)

## Cook-Levin Details

- SAT is in NP because

$$(x_1 \vee x_2) \wedge (x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2)$$

- it is a decision problem
- whether a given assignment of values actually satisfies the expression can be checked in polynomial time

## Cook-Levin Details

Ingredients – building a boolean expression to represent the Turing machine's task

- boolean variables represent the state of the Turing machine as it executes its program

Variables	Intended interpretation	How many?
$T_{ijk}$	True if tape cell $i$ contains symbol $j$ at step $k$ of the computation.	$O(p(n)^2)$
$H_{ik}$	True if the $M$ 's read/write head is at tape cell $i$ at step $k$ of the computation.	$O(p(n)^2)$
$Q_k$	True if $M$ is in state $q$ at step $k$ of the computation.	$O(p(n))$

[http://en.wikipedia.org/wiki/Cook-Levin\\_theorem](http://en.wikipedia.org/wiki/Cook-Levin_theorem)

- $p(n)$  = number of steps required for the Turing machine to accept or reject an input
  - polynomial function because it solves a problem in NP

## Cook-Levin Details

- expressions involving those variables represent the machine's input, goal, program, and rules of operation

Expression	Conditions	Interpretation	How many?
$T_{i0}$	Tape cell $i$ initially contains symbol $j$	Initial contents of the tape. For $i > n-1$ and $i < 0$ , outside of the actual input $i$ , the initial symbol is the special default/blank symbol.	$O(p(n))$
$Q_{s0}$		Initial state of $M$ .	1
$H_{00}$		Initial position of read/write head.	1
$T_{ijk} \rightarrow \neg T_{ij'k}$	$j \neq j'$	One symbol per tape cell.	$O(p(n)^2)$
$T_{ijk} \wedge T_{ij(k+1)} \rightarrow H_{ik}$	$j \neq j'$	Tape remains unchanged unless written.	$O(p(n)^2)$
$Q_k \rightarrow \neg Q_{q'k}$	$q \neq q'$	Only one state at a time.	$O(p(n))$
$H_{ik} \rightarrow \neg H_{i'k}$	$i \neq i'$	Only one head position at a time.	$O(p(n)^3)$
$(H_{ik} \wedge Q_{qk} \wedge T_{i\alpha k}) \rightarrow \bigvee_{\delta(H(i+d)(k+1) \wedge Q_{q(k+1)} \wedge T_{i\sigma(k+1)})} \delta(H(i+d)(k+1) \wedge Q_{q(k+1)} \wedge T_{i\sigma(k+1)})$	$k < p(n)$	Possible transitions at computation step $k$ when head is at position $i$ .	$O(p(n)^2)$
$\bigvee_{f \in F} Q_{fp(n)}$		Must finish in an accepting state.	1

[http://en.wikipedia.org/wiki/Cook-Levin\\_theorem](http://en.wikipedia.org/wiki/Cook-Levin_theorem)

## Cook-Levin Details

The transformation from Turing machine to instance of SAT is a polynomial-time reduction.

- $O(p(n)^2)$  variables
- $O(p(n)^3)$  clauses

Transforming the SAT solution to a solution for the NP problem is  $O(1)$ .

Thus, if SAT could be solved in polynomial time, so could any problem in NP.

## Hardness

Hard problems are at least as hard as the hardest problems in the class but may not be in the class itself.

**NP-hard** – set of problems that NP-complete problems can be reduced to

- all NP-complete problems are also NP-hard
- FNP versions of NP-complete problems are NP-hard
- there appear to be problems that are NP-hard but not NP-complete
  - e.g. determining whether or not a given chess board configuration is checkmate

## Common Myths

NP problems require exponential time.

Probably **yes**.

But technically **unknown**, because  $P \neq NP$  hasn't been proven.

- though it is generally thought that there are problems in NP that are not in P (and thus some problems in NP do require exponential time)

Also **no**, because there may be specific instances or classes of instances which can be solved in polynomial (or at least subexponential) time.

- e.g. maximum independent set – NP-hard/complete in general,  $O(n)$  for trees
- e.g. longest path – NP-hard/complete in general,  $O(n+m)$  for DAGs

## Common Myths

NP-complete problems are difficult because the search space is so large.

*framed as a series of choices, the running time depends on branching factor, longest path*

**No**, it's not the size of the search space as such, but that you have to look at so much of it.

- compare to greedy – and even many dynamic programming – algorithms

*these are also framed as a series of choices, but either only one option is needed for each choice (a branching factor of 1) or there are many repeated subproblems so most branches can be pruned*

## Common Myths

P is good and NP is bad.

**Not necessarily** –

- a polynomial-time algorithm may have large constant factors or exponents
- the exponential-time worst-case behavior may be rare
  - e.g. simplex algorithm for linear programming
- you might not need to solve large input sizes

## Harder than NP?

Are there any problems harder than NP?

**Yes.**

- e.g. Presburger arithmetic

## Presburger Arithmetic

Definition –

- contains constants 0 and 1 and the operator +
- axioms

```
1.  $\neg(0 = x + 1)$ 
2.  $x + 1 = y + 1 \rightarrow x = y$ 
3.  $x + 0 = x$ 
4.  $x + (y + 1) = (x + y) + 1$ 
5. Let  $P(x)$  be a first-order formula in the language of Presburger arithmetic with a free variable  $x$  (and possibly other free variables). Then the following formula is an axiom:
 $(P(0) \wedge \forall x(P(x) \rightarrow P(x + 1))) \rightarrow \forall y P(y).$ 
```

[http://en.wikipedia.org/wiki/Presburger\\_arithmetic](http://en.wikipedia.org/wiki/Presburger_arithmetic)

Why is Presburger arithmetic interesting?

- it is *decidable* – an algorithm exists to determine if any given statement is derivable from the axioms
- the decision problem has worst-case runtime  $2^{2^{cn}}$  for  $c > 0$
- there are theorems of length  $n$  whose proofs have doubly exponential length
  - implies that there are computational limits on what can be proven by computer programs

## Unknown Problems

Are there problems whose hardness is unknown?

Yes.

Two examples –

- graph isomorphism
  - given two graphs  $G$  and  $H$ , determine if there is mapping  $f$  from vertices of  $G$  to vertices of  $H$  such that if  $(x, y)$  is an edge of  $G$ ,  $(f(x), f(y))$  is an edge of  $H$
  - thought to be between P and NP-complete – can often be solved quickly in practice
- integer factorization
  - given integers  $n$  and  $m$ , does  $n$  have a factor at most  $m$ ?
  - known to be in both NP and co-NP, thought to not be in P or NP-complete
    - co-NP = can verify “no” answer in polynomial time
  - primality testing is in P

## Other Complexity Classes

**PSPACE** – decision problems which can be solved by a Turing machine needing only polynomial space

**EXSPACE** – decision problems which can be solved by a Turing machine needing an exponential amount of space

- how does PSPACE compare to P and NP?
  - bigger (probably)
- does EXSPACE contain PSPACE?
  - yes
- are there problems in EXSPACE that aren't in PSPACE?
  - yes

## Many Interesting Problems are NP-Complete

MY HOBBY:  
EMBEDDING NP-COMPLETE PROBLEMS IN RESTAURANT ORDERS

**CHOTCHKIES RESTAURANT**

~ APPETIZERS ~

MIXED FRUIT	2.15
FRENCH FRIES	2.75
SIDE SALAD	3.35
HOT WINGS	3.55
MOZZARELLA STICKS	4.20
SAMPLER PLATE	5.80

~ SANDWICHES ~

BARBECUE	6.55
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WED LIKE EXACTLY \$15.05 WORTH OF APPETIZERS, PLEASE.

... EXACTLY? UHH ...

HERE, THESE PAPERS ON THE KNAPSACK PROBLEM MIGHT HELP YOU OUT.

LISTEN, I HAVE SIX OTHER TABLES TO GET TO –

– AS FAST AS POSSIBLE, OF COURSE. WANT SOMETHING ON TRAVELING SALESMAN?

<http://xkcd.com/287/>

## Many Interesting Problems Are NP-Complete

More than 3000 NP-complete problems are known.

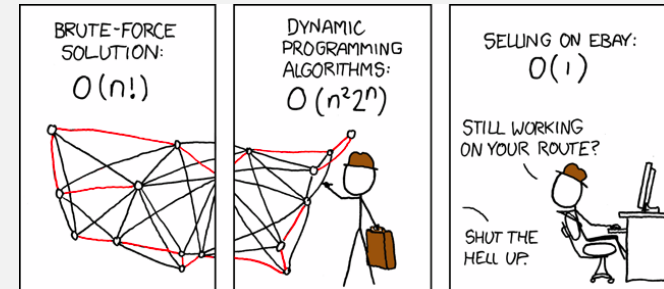
- [http://en.wikipedia.org/wiki/List\\_of\\_NP-complete\\_problems](http://en.wikipedia.org/wiki/List_of_NP-complete_problems)

traveling salesman	min cost hamiltonian cycle
closest string	find a string with minimum distance to all other strings in a set
art gallery problem	minimum number of guards to cover all hallways
berth allocation problem	assignment of ships to berths in port to minimize service time, minimize delayed departures, optimize fuel consumption, etc
generalized assignment	assignment of agents to tasks so as to not exceed the agents' budget and the total profit of the assignment
maximum common subgraph isomorphism	applications in cheminformatics
multiprocessor scheduling	min time required to schedule jobs on multiple processors
vehicle routing	minimize cost of distribution of goods from central warehouses to customers
bin packing	pack objects into bins to minimize number of bins (e.g. loading trucks, backing up files onto removable media)
register allocation	assign variables to available registers

note: most of these descriptions are for the function version of the problem – technically not in NP, but the function version isn't any easier than the decision version

## So...

...you need to solve an NP-complete (or -hard) problem.  
What do you do?



<http://xkcd.com/399/>

## Tactics

- dodge the bullet
  - you may not need to solve for large inputs
  - you may only need to solve for a special class of inputs which have an efficient algorithm
- bite the bullet
  - recursive backtracking – clever pruning!
  - branch-and-bound – clever bound functions!
- settle for good enough
  - heuristics – clever tricks which seem to work well, but without guarantees on runtime or solution quality
  - approximation algorithms – with bounds on the quality of the approximation